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INTERNATIONAL APPLICATION NO.	INTERNATIONAL FILING DATE	PRIORITY DATE CLAIMED
PCT/JP00/07410	24 October 2000	27 October 1999
TITLE OF INVENTION		
LINEAR MOTOR		
APPLICANT(S) FOR DO/EO/US		
YAMAMOTO, Hideo, SHIBUYA, Koyo		
Applicant herewith submits to the United States Designated/Elected Office (DO/EO/US) the following items and other information:		
<p>1. <input checked="" type="checkbox"/> This is a FIRST submission of items concerning a filing under 35 U.S.C. 371</p> <p>2. <input type="checkbox"/> This is a SECOND or SUBSEQUENT submission of items concerning a filing under 35 U.S.C. § 371.</p> <p>3. <input checked="" type="checkbox"/> This express request to begin national examination procedures (35 U.S.C. 371(f)) at any time rather than delay examination until the expiration of the applicable time limit set in 35 U.S.C. 371(b) and PCT Articles 22 and 39(1).</p> <p>4. <input type="checkbox"/> A proper Demand for International Preliminary Examination was made by the 19th month from the earliest claimed priority date.</p> <p>5. <input checked="" type="checkbox"/> A copy of the International Application as filed (35 U.S.C. 371(c)(2))</p> <p style="margin-left: 20px;">a. <input type="checkbox"/> is transmitted herewith (required only if not transmitted by the International Bureau).</p> <p style="margin-left: 20px;">b. <input checked="" type="checkbox"/> has been transmitted by the International Bureau.</p> <p style="margin-left: 20px;">c. <input type="checkbox"/> is not required, as the application was filed in the United States Receiving Office (RO/US).</p> <p>6. <input checked="" type="checkbox"/> A translation of the International Application into English (35 U.S.C. 371(c)(2)).</p> <p>7. <input type="checkbox"/> Amendments to the claims of the International Application under PCT Article 19 (35 U.S.C. 371(c)(3))</p> <p style="margin-left: 20px;">a. <input type="checkbox"/> are transmitted herewith (required only if not transmitted by the International Bureau).</p> <p style="margin-left: 20px;">b. <input type="checkbox"/> have been transmitted by the International Bureau.</p> <p style="margin-left: 20px;">c. <input type="checkbox"/> have not been made; however, the time limit for making such amendments has NOT expired.</p> <p style="margin-left: 20px;">d. <input type="checkbox"/> have not been made and will not be made.</p> <p>8. <input type="checkbox"/> A translation of the amendments to the claims under PCT Article 19 (35 U.S.C. 371(c)(3)).</p> <p>9. <input checked="" type="checkbox"/> An oath or declaration of the inventor(s) (35 U.S.C. 371(c)(4)).</p> <p>10. <input type="checkbox"/> A translation of the Annexes to the International Preliminary Examination Report under PCT Article 36 (35 U.S.C. 371(c)(5)).</p> <p>Items 11. to 16. below concern other document(s) or information included:</p> <p>11. <input type="checkbox"/> An Information Disclosure Statement under 37 CFR 1.97 and 1.98.</p> <p>12. <input checked="" type="checkbox"/> An assignment document for recording. A separate cover sheet in compliance with 37 CFR 3.28 and 3.31 is included.</p> <p>13. <input type="checkbox"/> A FIRST preliminary amendment.</p> <p style="margin-left: 20px;"><input type="checkbox"/> A SECOND or SUBSEQUENT preliminary amendment.</p> <p>14. <input type="checkbox"/> A substitute specification.</p> <p>15. <input type="checkbox"/> A change of power of attorney and/or address letter</p> <p>16. <input checked="" type="checkbox"/> Other items or information:</p>		
Copy of the International Search Report, with English translation		

U.S. APPLICATION NO. (if known, see 37 CFR 1.53) 09/869268		INTERNATIONAL APPLICATION NO. PCT/JP00/07410		ATTORNEY'S DOCKET NUMBER 1900/00027	
<input checked="" type="checkbox"/> The following fees are submitted: Basic National Fee (37 CFR 1.492(a)(1)-(5)): Search Report has been prepared by the EPO or JPO.....\$860.00 International preliminary examination fee paid to USPTO (37 CFR 1.482)\$690.00 No international preliminary examination fee paid to USPTO (37 CFR 1.482) but international search fee paid to USPTO (37 CFR 1.445(a)(2)).....\$710.00 Neither international preliminary examination fee (37 CFR 1.482) nor international search fee (37 CFR 1.445(a)(2)) paid to USPTO.....\$1,000.00 International preliminary examination fee paid to USPTO (37 CFR 1.482) and all claims satisfied provisions of PCT Article 33(2)-(4).....\$100.00				CALCULATIONS	PTO USE ONLY
ENTER APPROPRIATE BASIC FEE AMOUNT =				\$860.00	
Surcharge of \$130.00 for furnishing the oath or declaration later than <input type="checkbox"/> 20 <input type="checkbox"/> 30 months from the earliest claimed priority date (37 CFR 1.492(e)).				\$0.00	
Claims	Number Filed	Number Extra	Rate		
Total Claims	16 - 20 =	0	X \$18.00	\$0.00	
Independent Claims	2 - 3 =	0	X \$80.00	\$0.00	
Multiple dependent claim(s)(if applicable)			+ \$270.00	\$270.00	
TOTAL OF ABOVE CALCULATIONS =				\$1,130.00	
Reduction by 1/2 for filing by small entity, if applicable.				\$0.00	
SUBTOTAL =				\$1,130.00	
Processing fee of \$130.00 for furnishing the English translation later than <input type="checkbox"/> 20 <input type="checkbox"/> 30 months from the earliest claimed priority date (37 CFR 1.492(e)).				\$0.00	
TOTAL NATIONAL FEE =				\$1,130.00	
Fee for recording the enclosed assignment (37 CFR 1.21(h)). The assignment must be accompanied by an appropriate cover sheet (37 CFR 3.28, 3.31). \$40.00 per property +				\$40.00	
TOTAL FEES ENCLOSED =				\$1,170.00	
				Amount to be:	
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a. <input checked="" type="checkbox"/> A check in the amount of \$1,170.00 to cover the above fees is enclosed. b. <input type="checkbox"/> Please charge my Deposit Account No. <u>22-0185</u> in the amount of \$_____ to cover the above fees. A duplicate copy of this sheet is enclosed. c. <input checked="" type="checkbox"/> The Director is hereby authorized to charge any additional fees which may be required, or credit any overpayment to Deposit Account No. <u>22-0185</u> . A duplicate copy of this sheet is enclosed.					
NOTE: Where an appropriate time limit under 37 CFR 1.494 or 1.495 has not been met, a petition to revive (37 CFR 1.137(a) or (b) must be filed and granted to restore the application to pending status SEND ALL CORRESPONDENCE TO: Connolly Bove Lodge & Hutz LLP 1990 M Street, N.W., Suite 800 Washington, DC 20036-3425					
Signature: <u>Patrick Wells 46,355</u> NAME: <u>Morris Liss</u> REGISTRATION NUMBER: <u>24,510</u>					

SPECIFICATION

LINEAR MOTOR

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FIELD OF THE INVENTION

The present invention relates to a movable magnet type linear motor with the purpose of improving motor efficiency and of simplifying the manufacture of the motor.

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BACKGROUND ART

In recent years, fervent efforts have been made on the development of linear motor.

Japanese Patent Application 10-118358 describes a conventional type linear motor.

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Description will be given below on the conventional type linear motor as described above referring to the drawings.

Fig. 14 is a cross-sectional plan view of a conventional type linear motor, and Fig. 15 is a cross-sectional view along the line A—A in Fig. 14.

20

An inner yoke 1 is designed in form of quadratic prism by laminating a multiple of thin plates 2, each of which is in approximately rectangular shape and has high magnetic permeability. An outer yoke 3 is designed in form of quadratic prism by laminating a multiple of thin plates 4, each of which is in approximately rectangular shape and has high magnetic permeability. Slots 6 and 7 are cut out in axial

25

direction 5, and three magnetic poles 8, 9 and 10 are formed. The surface of the outer yoke 3 having the magnetic poles 8, 9 and 10 is directed toward the inner yoke

1 and a yoke block 12 is formed with a given gap 11 between them. A set of yoke blocks is retained on a base 13 so that the inner yokes are arranged at positions opposite to each other with a given spacing.

Coils 14 are wound around the central magnetic pole 9 so that different magnetic poles are alternately formed at three magnetic poles 8, 9 and 10 of outer yoke 3. The coils 14 are independently wound on two outer yokes 3, and the coils 14 are connected in parallel.

A movable unit 15 comprises a pair of planar permanent magnets 16 and 17 magnetized in opposed directions of the inner yoke 1 and the outer yoke 3, a permanent magnet holder 18, and a shaft 19. The permanent magnets 16 and 17 are fixed by a permanent magnet holder 18 with a given spacing in axial direction so that directions of magnetization are opposite to each other, and these magnets are disposed in the gap 11 between the inner yoke 1 and the outer yoke 3.

Description will be given now on operation of the linear motor with the above arrangement.

A magnetic flux generated from the permanent magnet 16 passes through the gap 11, the inner yoke 1, the gap 11, the permanent magnet 17, the outer yoke 3, and the gap 11 and returns to the permanent magnet 16, and a static magnetic field is generated in the gap 11. In the inner yoke 1 and the outer yoke 3, the magnetic flux circulates in the planes of the thin plates 2 and 4.

When AC current is supplied to the coil 14, different magnetic poles are alternately generated in axial direction at the magnetic poles 8, 9, and 10. By magnetically attracting and repelling action of the permanent magnets 16 and 17 of the movable unit 15, thrust force is generated, which is proportional to the magnitude of electric current flowing through the coil 14 and to magnetic flux density of the

permanent magnets 16 and 17. Then, the shaft 19 is reciprocally moved together with the movable unit 15 in synchronization with the frequency of AC current.

The conventional arrangement as described above is advantageous in that the inner yoke 1 and the outer yoke 3 can be manufactured in easier manner.

5 However, planar permanent magnets 16 and 17 are arranged in parallel in the gap 11 between the inner yoke 1 and the outer yoke 3 each designed in form of quadratic prism. When the shaft 19 is disposed at axially rotated position during manufacture, balance is lost in the distance between the permanent magnets 16 and 17 and the inner yoke 1 or the distance between the permanent magnets 16 and 17 and the outer yoke 3. This leads to instability of the thrust force of the linear motor.

DISCLOSURE OF THE INVENTION

To solve the above problems of the conventional example, it is an object of the present invention to provide a linear motor, in which the thrust force of the linear motor is not turned to unstable even when the shaft 19 is disposed at axially rotated position during manufacture and motor efficiency can be improved and yokes can be manufactured in easier manner.

Also, when the permanent magnets 16 and 17 are disposed at deviated positions closer to the inner yoke 1 or to the outer yoke 3 during manufacture, balance is lost in the distance between the permanent magnets 16 and 17 and the inner yoke 1 or in the distance between the permanent magnets 16 and 17 and the other yoke 3. Thus, the force to directly attract the permanent magnets 16 and 17 toward the inner yoke 1 or the outer yoke 3 is increased. As a result, sliding loss is increased on the bearings 20 via the movable unit 15 and the shaft 19.

It is another object of the present invention to provide a linear motor, in which, even when permanent magnets are disposed at deviated positions closer to the inner yoke or the outer yoke during manufacture, the force to directly attract the permanent magnets toward the inner yoke or the outer yoke is not increased, and
5 the motor efficiency is improved, and the yokes can be manufactured in easier manner.

To solve these problems, the linear motor according to the present invention comprises a movable unit in cylindrical shape and having the central axis at the intersection of X-axis and Y-axis, an inner yoke arranged on inner side of the
10 movable unit with a given spacing in radial direction of the movable unit and being formed by laminating a multiple of thin plates each in approximately rectangular shape and having high magnetic permeability arranged in parallel to one of X-axis or Y-axis, an outer yoke arranged on outer side of the movable unit with a given
spacing in radial direction of the movable unit and being formed by laminating a
15 multiple of thin plates each in approximately rectangular shape and having high magnetic permeability arranged in the same direction as the thin plates of the inner yoke, and a pair of permanent magnets magnetized in a direction to connect the inner yoke with the outer yoke and mounted on the movable unit to be retained in a gap between the inner yoke and the outer yoke.

20 As a result, even when the shaft is disposed at axially rotated position during the manufacture, the thrust force of the linear motor is not turned to unstable. Iron loss of the inner yoke and the outer yoke is reduced. Motor efficiency is improved, and this facilitates the manufacture of the linear motor.

Also, the present invention provides the linear motor as described above,
25 wherein a pair of permanent magnets magnetized in radial direction around the

central axis are arranged with a given spacing in parallel to the central axis so that directions of magnetization are opposite to each other, and the magnets being retained in a gap between the inner yoke and the outer yoke.

With such an arrangement, even when the permanent magnets are disposed
5 at deviated positions closer to the inner yoke or the outer yoke, the force to directly attract the permanent magnets toward the inner yoke or the outer yoke is not increased.

Further, the present invention provides the linear motor as described above,
wherein the inner yoke is formed by laminating a multiple of thin plates of the same
10 shape and the same dimension, and the outer yoke is formed by laminating a multiple of thin plates of the same shape and the same dimension.

As a result, it is possible to manufacture the linear motor in easier manner.

Also, the present invention provides the linear motor as described above,
wherein radius of curvature of inner periphery of the outer yoke is equal to radius of
15 curvature of inner periphery of the slot, and radius of curvature of outer periphery of the outer yoke is equal to radius of curvature of outer periphery of the slot, and radius of curvature of outer periphery of the outer yoke or the slot is greater than the radius of curvature of the inner periphery of the outer yoke or the slot.

As a result, it is possible to design the linear motor in compact size.

20 Further, the present invention provides the linear motor as described above,
wherein outer peripheral end of each of the outermost sides in laminating direction of the thin plates of the inner yoke and an end surface of the permanent magnet are on a line, which connects inner peripheral end of each of the outermost sides in laminating direction of the thin plates of the outer yoke with the intersection of X-axis
25 and Y-axis.

Accordingly, it is possible to reduce the amount of magnets.

Also, the present invention provides the linear motor as described above, wherein two inner yokes are arranged symmetrically with respect to Y-axis, and the two inner yokes are integrated by two inner yoke support members disposed inside
5 the inner yoke and positioned separately in direction of Y-axis.

As a result, the inner yoke can be integrated to a single component, and this facilitates the assembling procedure.

Further, the present invention provides the linear motor as described above, wherein two outer yokes are arranged symmetrically with respect to Y-axis, and the
10 two outer yokes are integrated by two outer yoke support members disposed on each of the outermost sides in laminating direction of the thin plates of the outer yokes.

As a result, the outer yokes can be integrated to a single component, and this facilitates the assembling procedure.

15 Also, the present invention provides a linear motor, which comprises a movable unit in cylindrical shape having central axis thereof at the intersection of X-axis and Y-axis, an inner yoke arranged on inner side of the movable unit with a given spacing in radial direction of the movable unit and being formed by laminating a multiple of thin plates each in approximately rectangular shape and having high
20 magnetic permeability arranged in parallel to one of X-axis or Y-axis, an outer yoke arranged on outer side of the movable unit with a given spacing in radial direction of the movable unit and being formed by laminating a multiple of thin plates each in approximately rectangular shape and having high magnetic permeability arranged in the same direction as the thin plates of the inner yoke, a base in planar shape for
25 retaining the inner yoke and the outer yoke, a cylinder mounted on the base as to be

positioned at the center of X-axis and Y-axis, a piston designed to retain a pair of permanent magnets magnetized in a direction to connect the inner yoke with the outer yoke and retained in a gap between the inner yoke and the outer yoke, provided at forward end of a shaft integrated with the movable unit and placed in the cylinder, and a spring mounted on the shaft.

As a result, even when the permanent magnets are disposed at deviated position closer to the inner yoke or the outer yoke, the force to directly attract the permanent magnets toward the inner yoke or the outer yoke is not increased. Therefore, sliding loss between the piston and the cylinder is also not increased, and this facilitates the manufacture of the linear motor.

Further, the present invention provide a linear motor, which comprises a movable unit in cylindrical shape and having the central axis at the intersection of X-axis and Y-axis, an inner yoke arranged on inner side of the movable unit with a given spacing in radial direction of the movable unit and being formed by laminating a multiple of thin plates each in approximately rectangular shape and having high magnetic permeability arranged in parallel to one of X-axis or Y-axis, an outer yoke arranged on outer side of the movable unit with a given spacing in radial direction of the movable unit, being formed by laminating a multiple of thin plates each in approximately rectangular shape and having high magnetic permeability arranged in the same direction as the thin plates of the inner yoke, and forming a first magnetic pole, a second magnetic pole and a third magnetic pole by arranging two slots cut out in the laminating direction of the thin plates, a coil wound on the second magnetic pole of the outer yoke and forming alternately different magnetic poles at the first magnetic pole, the second magnetic pole and the third magnetic pole, a base in planar shape for retaining the inner yoke and the outer yoke, bearings mounted on

10 According to another aspect of the present invention, a pair of permanent magnets magnetized in radial direction around the central axis are retained in a gap between the inner yoke and the outer yoke with a given spacing in parallel to the central axis so that directions of magnetization are opposite to each other. Even when the permanent magnets are disposed at deviated positions closer to the inner
15 yoke or the outer yoke during manufacture, the force to directly attract the permanent magnets toward the inner yoke or the outer yoke is not increased, and sliding loss on the sliding portions can be reduced.

According to still another aspect of the present invention, the inner yoke is formed by thin plates of the same shape and the same dimension, and the outer yoke is formed by thin plates of the same shape and the same dimension. Because the inner yoke and the outer yoke can be easily manufactured, this facilitates the manufacture of the linear motor.

According to still another aspect of the present invention, radius of curvature of inner periphery of the outer yoke is equal to radius of curvature of inner periphery of the slot, and radius of curvature of outer periphery of the outer yoke is equal to radius

of curvature of outer periphery of the slot. Radius of curvature of outer periphery of the outer yoke or the slot is greater than the radius of curvature of inner periphery of the outer yoke or the slot. This makes it possible to design the linear motor in compact size.

5 According to still another aspect of the present invention, it is designed in such manner that outer periphery of each of the outermost sides in laminating direction of the thin plates of the inner yoke and an end surface of the permanent magnets are on a line, which connects inner periphery of each of the outermost sides in laminating direction of the thin plates of the outer yoke with the intersection of X-axis
10 and Y-axis. As a result, the amount of magnets can be reduced.

According to still another aspect of the present invention, two inner yokes are disposed symmetrically with respect to Y-axis, and the two inner yokes are integrated by two inner yoke support members provided inside the two inner yokes and positioned separately in direction of Y-axis. As a result, the two inner yokes
15 can be integrated to a single component, and this facilitates the assembling procedure.

According to still another aspect of the present invention, two outer yokes are disposed symmetrically with respect to Y-axis, and the two outer yokes are integrated by two outer yoke support members arranged at each of the outermost
20 sides in laminating direction of the thin plates of the two outer yokes. As a result, the two outer yokes are integrated to a single component, and this facilitates the assembling of the linear motor.

According to still another aspect of the present invention, the linear motor comprises a movable unit of cylindrical shape having central axis thereof at the
25 intersection of X-axis and Y-axis, an inner yoke arranged on inner side of the

movable unit with a given spacing in radial direction of the movable unit and being formed by laminating a multiple of thin plates each in approximately rectangular shape and having high magnetic permeability in parallel to one of X-axis or Y-axis, an outer yoke arranged on outer side of the movable unit with a given spacing in radial direction of the movable unit and being formed by laminating a multiple of thin plates each in approximately rectangular shape and having high magnetic permeability in the same direction as the thin plates of the inner yoke, a base in planar shape for retaining the inner yoke and the outer yoke, a cylinder mounted on the base as to be positioned at the center of X-axis and Y-axis, a pair of permanent magnets magnetized in a direction to connect the inner yoke with the outer yoke and arranged on the movable unit to be retained in a gap between the inner yoke and the outer yoke with a given spacing in parallel to the central axis so that directions of magnetization are opposite to each other, a piston disposed at forward end of a shaft integrated with the movable unit and placed in the cylinder, and a spring mounted on the shaft. Even when the permanent magnets are disposed at deviated position closer to the inner yoke or the outer yoke, the force to directly attract the permanent magnets toward the inner yoke or the outer yoke is not increased. Therefore, sliding loss between the piston and the cylinder is not increased, and this facilitates the manufacture of the linear motor.

BRIEF DESCRIPTION OF THE DRAWINGS

Fig. 1 is a cross-sectional plan view of a linear motor of a first embodiment of the present invention;

Fig. 2 is a cross-sectional view along X-axis in Fig. 1;

Fig. 3 is a cross-sectional plan view of a linear motor of a second embodiment

of the present invention;

Fig. 4 is a cross-sectional plan view of a linear motor of a third embodiment of the present invention;

Fig. 5 is a front view of a thin plate to make up an inner yoke in the above
5 embodiment;

Fig. 6 is a front view of a thin plate to make up an outer yoke in the above embodiment;

Fig. 7 is a cross-sectional front view of a linear motor of a fourth embodiment of the present invention;

Fig. 8 is a cross-sectional view along the line A – A in Fig. 7;
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Fig. 9 is a cross-sectional plan view of a linear motor of a fifth embodiment of the present invention;

Fig. 10 is a plan view of an inner yoke of a sixth embodiment of the present invention;

Fig. 11 is a front view of the inner yoke of the above embodiment;
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Fig. 12 is a plan view of an outer yoke of a seventh embodiment of the present invention;

Fig. 13 is a cross-sectional front view of a linear compressor of an eighth embodiment of the present invention;

Fig. 14 is a cross-sectional plan view of a conventional type linear motor; and
20

Fig. 15 is a cross-sectional front view of a conventional type linear motor.

BEST MODE FOR CARRYING OUT THE INVENTION

Description will be given below on embodiments of a linear motor of the
25 present invention referring to the drawings.

(Example 1)

Fig. 1 is a cross-sectional plan view of a first embodiment of a linear motor of the present invention, and Fig. 2 is a cross-sectional view along X-axis in Fig. 1.

A movable unit 21 has its central axis at an intersection of X and Y axes. An
5 inner yoke 22 is disposed on inner side of the movable unit 21 with a gap 38 of a
predetermined spacing in radial direction of the movable unit 21, and a multiple of
thin plates 23 each in approximately rectangular shape and having high magnetic
permeability are laminated in axial direction of one of X-axis or Y-axis. An outer
yoke is disposed on outer side of the movable unit 21 with a gap 39 of a
10 predetermined spacing in radial direction of the movable unit 21. A multiple of thin
plates 25 each in approximately rectangular shape and having high magnetic
permeability are laminated one upon another in the same direction as the thin plates
23 of the inner yoke 22 as described above. Two slots 26 and 27 are cut out in
laminating direction of the thin plates 25, and a first magnetic pole 28, a second
15 magnetic pole 29, and a third magnetic pole 30 are formed.

A surface of the outer yoke 24 having the magnetic poles 28, 29 and 30 is
retained on a planar base 89 at a position opposite to the inner yoke 22 so that a
magnetic path 20 is formed along the surfaces of the thin plates 23 and 25.

Coils 32 are wound around the second magnetic pole 29 so that different
20 magnetic poles are provided alternately on the three magnetic poles 28, 29 and 30
of the outer yoke 24. The coils 32 are wound on the two outer yokes 24 individually,
and coils 32 are electrically connected in parallel.

Here, magnetic steel trip (35H440; manufactured by Nippon Steel Corporation)
is used as the thin plates 23 and 25, which make up the inner yokes 22 and the
25 outer yokes 24 respectively. The surface of each thin plate has highly saturated

magnetic flux density and low core loss, and the surface is provided with an insulating film.

The movable unit 21 comprises a pair of a first permanent magnet 33 and a second permanent magnet 34 in C-shaped or cylindrical shape magnetized in a direction connecting the inner yoke 22 with the outer yoke 24, and a permanent magnet holder 35 and a shaft 36. A magnet of rare earth element of Nd-Fe-B type is preferably used as the first permanent magnet 33 and the second permanent magnetic 34. These permanent magnets are fixed by the permanent magnet holder 35 with a given spacing and in parallel to the central axis so that directions of magnetization are opposite to each other, and these are disposed in a gap between the inner yoke 22 and the outer yoke 24.

As bearings 37 used to smoothly move the shaft 36 in reciprocal movement, linear ball bearings, oil-retaining metal bearings, etc. as conventionally used may be selected.

Now, description will be given on operation of a linear motor with the above arrangement.

A magnetic path 20 (shown by solid line) of magnetic fluxes generated from the first permanent magnet 33 and the second permanent magnet 34 encloses the slot 26 or the slot 27. It passes through the first permanent magnet 33, the gap 38, the inner yoke 22, the gap 38, the second permanent magnet 34, the gap 39, the outer yoke 24, and the gap 39 and returns to the first permanent magnet 33 and generates static magnetic fields in the gaps 38 and 39. In the inner yoke 22 and the outer yoke 24, it circulates in the planes of the thin plates 23 and 25.

When AC current is supplied to the coil 32, different magnetic poles are alternately generated in axial direction on the first magnetic pole 28, the second

magnetic pole 29, and the third magnetic pole 30. By magnetic attraction and repulsion of the movable unit 21 with respect to the first permanent magnet 33 and the second permanent magnet 34, there occurs an axial thrust force proportional to the magnitude of electric current and to magnetic flux density of the fluxes generated from the first permanent magnet 33 and the second permanent magnet 34. Then, the shaft 36 is moved reciprocally together with the movable unit 21 in synchronization with the frequency of AC current.

In this case, the movable unit 21 is designed in cylindrical shape, and the inner yoke 22 and the outer yoke 24 are disposed on inner side and outer side of the movable unit 21 respectively with a given spacing in radial direction of the movable unit 21 in the gaps 38 and 39. The first permanent magnet 33 and the second permanent magnet 34 are magnetized in the direction from the inner yoke 22 to the outer yoke 24.

Therefore, even when the shaft 36 is disposed at axially rotated position during manufacture, balance is kept well in the distance between the first permanent magnet 33 or the second permanent magnet 34 and the inner yoke, or in the distance between the first permanent magnet 33 or the second permanent magnet 34 and the outer yoke 24 because the movable unit 21 is designed in cylindrical shape. Thus, thrust force of the linear motor is not turned to unstable.

The inner yoke 22 and the outer yoke 24 can be produced by laminating a multiple of the thin plates 23 and 25 each in approximately rectangular shape and having high magnetic permeability, and this contributes to simplification of the manufacture of the linear motor.

The magnetic path 20 of the magnetic fluxes generated from the first permanent magnet 33 and the second permanent magnet 34 circulates in the

planes of the thin plates 23 and 25 in the inner yoke 22 and the outer yoke 24.

When the magnetic fluxes circulate in the planes of the thin plates 23 and 25, they tend to generate eddy current in a direction to cross the magnetic fluxes. This is electric current which is proportional to square of the magnetic flux density and is

5 also proportional to square of plate thickness of the material of the yoke. Because the inner yoke 22 and the outer yoke 24 are made up with a multiple of thin plates 23 and 25 each having high magnetic permeability and with insulated surface, it is possible to eliminate generation of eddy current almost completely, and to extensively reduce iron loss. As a result, motor efficiency can be improved.

10 As described above, the linear motor according to the present embodiment comprises a movable unit in cylindrical shape with its central axis at an intersection of X-axis and Y-axis, an inner yoke disposed on inner side of the movable unit with a given spacing in radial direction of the movable unit and a multiple of thin plates each in approximately rectangular shape and having high magnetic permeability and
15 laminated in parallel to one of X-axis or Y-axis, an outer yoke disposed on outer side of the movable unit with a given spacing in radial direction of the movable unit and being formed by laminating a multiple of thin plates each in approximately rectangular shape and having high magnetic permeability, the thin plates being
20 and having a first magnetic pole, a second magnetic pole and a third magnetic pole in two slots which are cut out in laminating direction of the thin plates, a coil wound on the second magnetic pole of the outer yoke and forming alternately different magnetic poles on the first, the second and the third magnetic poles, a base for retaining the inner yoke and the outer yoke, bearings mounted on the base so as to
25 be positioned at the center of the X-axis and Y-axis respectively, and a pair of

permanent magnets magnetized in a direction to connect the inner yoke with the outer yoke and provided on the movable unit and retained in a gap between the inner yoke and the outer yoke with a given spacing in parallel to the central axis so that directions of magnetization are opposite to each other. Because the movable unit is designed in cylindrical shape even in case the shaft is arranged at axially rotated position at the time of manufacture, the thrust force of the linear motor is not turned to unstable. Iron loss of the inner yoke and the outer yoke is reduced and motor efficiency is improved, and the procedure to manufacture the linear motor can be simplified.

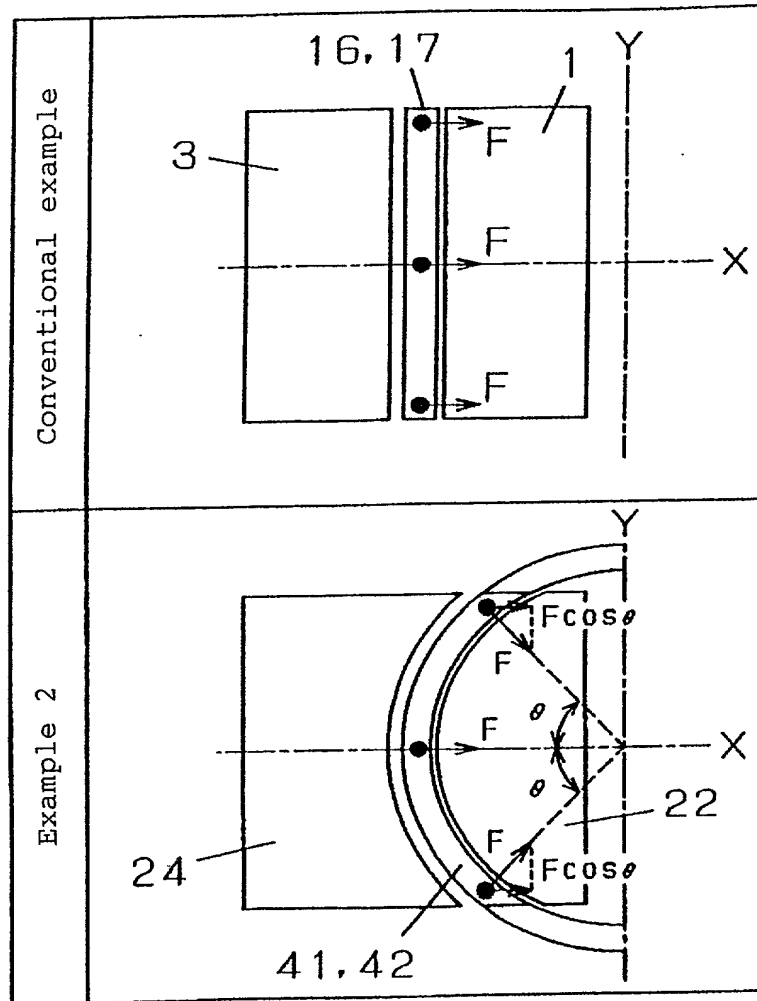
10 In the present embodiment, two sets each of the inner yokes and the outer yokes are used, while the same effect can be obtained when three sets or more of these yokes are used.

(Example 2)

Fig. 3 is a cross-sectional plan view of a second embodiment of the linear motor of the present invention. Cross-sectional view along X-axis of the linear motor is the same as Fig. 2 as given above.

According to the present embodiment, in the linear motor of Example 1, there are provided a pair of a first permanent magnet 41 and a second permanent magnet 42 in C-shaped or cylindrical shape and magnetized in radial direction around the central axis. The first permanent magnet 41 and the second permanent magnet 42 are fixed by a permanent magnet holder 35 with a given spacing in axial direction so that directions of magnetization are alternately turned to opposite direction, and these are disposed in a gap between the inner yoke 22 and the outer yoke 24.

Table 1



In the conventional arrangement, planar permanent magnets 16 and 17 are disposed in parallel in a gap between an inner yoke 1 and an outer yoke 3 each in form of quadratic prism as shown in Table 1. In case the permanent magnets 16 and 17 are disposed at positions closer to the inner yoke 1 during manufacture, the force to attract the permanent magnets directly toward the inner yoke 1 is increased.

In the linear motor with the above arrangement, in case the first permanent magnet 41 and the second permanent magnet 42 are disposed at positions closer to the inner yoke 22 or to the outer yoke 24 (deviated in direction of X-axis) as shown in Table 1 during manufacture, the force to directly attract the permanent magnets 41 and 42 toward the inner yoke 22 or the outer yoke 24 is decreased. Specifically, if it is supposed that the force along X-axis is 1, the value of $\cos \theta$ is decreased as the angle θ is increased. Therefore, compared with the conventional case where the planar magnets 16 and 17 and the inner yoke 1 and the outer yoke 2 each in form of quadratic prism are used, the force to directly attract the permanent magnets 41 and 42 toward the inner yoke 22 or the outer yoke 24 (the force to attract in the direction of X-axis) is decreased, and sliding loss on the bearings 37 can be decreased.

Both the inner yoke 22 and the outer yoke 24 can be formed by laminating many thin plates 23 and 25 each in approximately rectangular shape and having high magnetic permeability, and the linear motor can be produced in easier manner.

As described above, the linear motor according to the present embodiment comprises an inner yoke and an outer yoke arranged at a given spacing in parallel to the central axis, and a pair of permanent magnets magnetized in radial direction around the central axis at the center are retained in a gap between the inner yoke and the outer yoke so that the directions of magnetization are opposite to each other. Even when the permanent magnets are arranged at deviated position closer to the inner yoke or the outer yoke, the force to directly attract the permanent magnets to the inner yoke or the outer yoke is not increased, and sliding loss on the bearings can be reduced.

(Example 3)

Fig. 4 is a cross-sectional plan view of a third embodiment of the linear motor of

the present invention. Fig. 5 is a front view of a thin plate of the inner yoke of the present invention, and Fig. 6 is a front view of a thin plate of the outer yoke of the present invention.

According to the present embodiment, in the linear motor as described in

- 5 Example 1 or 2, thin plates 51 each in approximately rectangular shape and designed in the same shape and in the same dimension and having high magnetic permeability are used to form the inner yoke 50, and a multiple of the thin plates are laminated in parallel to one of X-axis or Y-axis using a jig so that the radius R1 on outer periphery of the inner yoke 50 is smaller by a given value than the radius R2 on inner periphery of the movable unit 21.

- Also, thin plates 53 each in approximately rectangular shape and having high magnetic permeability and in the same shape and the same dimension are used as the outer yoke 52, and a multiple of the thin plates 53 are laminated in the same direction as the thin plates 51 of the inner yoke using a jig so that radius R3 on inner periphery of the outer yoke 52 is greater by a given value than radius R4 on outer periphery of the movable unit 21.

- In the linear motor with the above arrangement, thin plates of the same shape and the same dimension are laminated to form the inner yoke, and the thin plates of the same shape and the same dimension are laminated to form the outer yoke.
- 20 Because the inner yoke and the outer yoke can be formed in easier manner, this facilitates the manufacture of the linear motor.

(Example 4)

- Fig. 7 is a cross-sectional front view of a fourth embodiment of the linear motor of the present invention. Fig. 8 is a cross-sectional view along the line A – A in Fig.
- 25 7.

According to the present embodiment, in the linear motor of Example 1 or 2, thin plates 61 each in approximately rectangular shape and having high magnetic permeability are used for the outer yoke 60. It is designed in such manner that radius of curvature R5 of inner periphery of the outer yoke 60 is equal to radius of curvature R6 of inner periphery of a slot 62, and also that radius of curvature R7 of outer periphery of the outer yoke 60 is equal to radius of curvature R8 of outer periphery of the slot 62. It is designed in such manner that the radius of curvature R7 of outer periphery of the outer yoke and the radius of curvature R8 of outer periphery of the slot 62 are greater than the radius of curvature R5 of inner periphery of the outer yoke 60 and the radius of curvature R6 of inner periphery of the slot 62.

Specifically, on inner periphery of the outer yoke 60, if the center of X-axis and Y-axis is supposed to be the center of the radius of curvature R5, the center of the radius of curvature R6 is at a position deviated from the center of X and Y axes in the direction of X-axis by a dimension A of an opening of the slot 62. Also, on outer periphery of the slot 62, if the center of X and Y axes is supposed to be the center of the radius of curvature R8, outer periphery of the outer yoke 60 has its radius of curvature R7 at a position deviated from the center of X and Y axes in direction of X-axis, deviated by the dimension B on back portion of the outer yoke 60.

In the linear motor with the above arrangement, the radius of curvature R5 on inner periphery of the outer yoke 60 is equal to the radius of curvature R6 of inner periphery of the slot. Thus, in any of cross-sections in parallel to X-axis of the outer yoke 60, the dimension A of the opening of the slot 62 is the same. The radius of curvature R7 of outer periphery of the outer yoke 60 is equal to the radius of curvature R8 of outer periphery of the slot 62. Thus, in any of cross-sections in parallel to X-axis, it is equal to the dimension B on back portion of the outer yoke 60.

Therefore, in any of the thin plates of the outer yoke 60, the dimension A of the opening of the slot 62 is the same as the dimension B on back portion of the outer yoke 60.

Also, in the shape of the coil 63, a radius R10 of outer periphery of the coil 63 is greater than a radius R9 of inner periphery of the coil 63. The radius of curvature R7 of outer periphery of the outer yoke 60 and the radius of curvature R8 of outer periphery of the slot 62 are designed greater than the radius of curvature R5 of inner periphery of the outer yoke 60 and the radius of curvature R6 of the inner periphery of the slot 62. As a result, the coil 63 is adequately accommodated in the slot 62, and it is possible to design the linear motor in compact size.

As described above, in the linear motor of the present embodiment, the radius of curvature of inner periphery of the outer yoke is equal to the radius of curvature of inner periphery of the slot, and the radius of curvature of outer periphery of the outer yoke is equal to the radius of curvature of outer periphery of the slot. The radius of curvature of outer periphery of the outer yoke or the slot are greater than the radius of curvature of inner periphery of the outer yoke or the slot, and it is possible to design the linear motor in compact size.

(Example 5)

Fig. 9 is a cross-sectional plan view of a fifth embodiment of the linear motor of the present invention. The cross-sectional front view of the linear motor is the same as in Fig. 2 as given above.

According to this embodiment, in the linear motor of Example 2, it is designed in such manner that outer peripheral end D of each of the outermost sides of the thin plate 68 of the inner yoke 67 in laminating direction and an end surface of the permanent magnet are on a line, which connects an inner peripheral end C (of each

of the outermost sides of the thin plate 66 of the outer yoke 65 in laminating direction) with the intersection of X-axis and Y-axis.

A first permanent magnet 69 and a second permanent magnet 70 are magnetized in radial direction toward the central axis, and these magnets are fixed
5 by a permanent magnet holder 35 with a given spacing in axial direction so that the directions of magnetization are alternately directed in opposite direction, and these are arranged in a gap between the inner yoke 67 and the outer yoke 65.

Now, description will be given on operation of the linear motor with the above arrangement.

10 A magnetic path 31 (shown by $N \rightarrow S$) of magnetic fluxes generated from the first permanent magnet 69 and the second permanent magnet 70 encloses the slot 26 or the slot 27. Then, it passes via the first permanent magnet 69, the gap 38, the inner yoke 67, the gap 38, the second permanent magnet 70, the gap 39, the outer yoke 65, and the gap 39 and goes back to the first permanent magnet 69, and
15 static magnetic fields are generated in the gaps 38 and 39. The magnetic path 31 circulates in the planes of the thin plates 66 and 68 in the inner yoke 67 and the outer yoke 65. It circulates in the directions of magnetization of the first permanent magnet 69 and the second permanent magnet 70 respectively in the first permanent magnet 69 and the second permanent magnet 70 and in the gaps, i.e. in radial
20 direction toward the central axis.

Therefore, magnets can be fully utilized without waste, and the amount of magnets can be reduced.

As described above, according to the linear motor of the present embodiment, the outer periphery of each of the outermost sides of the thin plate of the inner yoke
25 in laminating direction and the end surface of the permanent magnet are on a line,

which connects the inner periphery of each of the outermost sides in laminating direction of the thin plates of the outer yoke with the intersection of X-axis and Y-axis. This makes it possible to reduce the amount of magnets.

(Example 6)

5 Fig. 10 is a plan view of an inner yoke in a sixth embodiment of the present invention. Fig. 11 is a front view, and overall arrangement as a linear motor is the same as in Fig. 1 and Fig. 2 as given above.

 According to the present embodiment, in the linear motor of Example 1 or 2, two inner yokes 71 are arranged symmetrically with respect to Y-axis, and the two
10 inner yokes 71 are integrated by two inner yoke support members 72, which are inside the inner yokes 71 and are positioned separately in direction of Y-axis. Each of the inner yoke support members 72 has a bolt hole 73, and it is used to fix the support member to a base 89.

 Therefore, the inner yokes are integrated to a single component, and this
15 facilitates the assembling procedure. Also, the accuracy of assembling with the movable unit 21 can be maintained in easier manner.

 As described above, in the linear motor of the present invention, two inner yokes are arranged symmetrically with respect to Y-axis, and the two inner yokes are integrated by two inner yoke support members, which are inside the two inner
20 yokes and are positioned separately in the direction of Y-axis. The inner yokes are integrated in a single component, and this facilitates the assembling procedure.

 If the inner yoke support members are made of nonmagnetic stainless steel such as SUS 304, iron loss can be reduced and motor efficiency can be improved.

(Example 7)

25 Fig. 12 is a plan view of an outer yoke in a seventh embodiment of the present

invention. Overall arrangement as a linear motor is the same as in Fig. 1 and Fig. 2 as given above.

According to the present embodiment, in the linear motor of Example 1 or 2, two outer yokes 75 are arranged symmetrically with respect to Y-axis, and the two
5 outer yokes 75 are integrated by two outer yoke support members 76 disposed at each of the outermost positions in laminating direction of the thin plates of the outer yokes. Each of the outer yokes 76 has a hole for bolt 77, and these are used to fix the support members to a base 89.

Therefore, the outer yokes are integrated to a single component, and this
10 facilitates the assembling procedure. Also, the accuracy of assembling with the movable unit 21 can be maintained in easier manner.

As described above, in the linear motor of the present embodiment, two outer yokes are arranged symmetrically with respect to Y-axis, and the two outer yokes are integrated by two outer yoke support members arranged at each of the
15 outermost sides in laminating direction of the thin plates of the two outer yokes. The two outer yokes are integrated to a single component, and this facilitates the assembling procedure.

If the outer yoke support members are made of nonmagnetic stainless steel such as SUS 304, iron loss can be reduced and motor efficiency can be improved.
20 (Example 8)

Fig. 13 is a cross-sectional front view of an eighth embodiment of a linear compressor according to the present invention.

A linear compressor 80 comprises a cylinder 81, a piston 82 placed in the cylinder 81 so that it can be reciprocally moved, a compression chamber 84 formed
25 as facing to a head 83 of the piston 82, and a suction valve 85 and a discharge valve

86 to be opened or closed in response to gas pressure in the compression chamber 84.

The linear compressor 80 comprises a linear motor 87 for reciprocally moving the piston 82 and a resonant spring 88 for supporting the piston 82 so that it can be
5 moved reciprocally.

The arrangement of the linear motor 87 is the same as the linear motor described in Example 1 and Example 2, and detailed description is not given here.

In the linear compressor 8 with the above arrangement, description will be given now on its operation.

10 A magnetic flux 31 coming out of an N pole of a first permanent magnet 33 passes through a gap 38, an inner yoke 22, the gap 38, an S pole of a second permanent magnet 34, an N pole of the permanent magnet 34, a gap 39, an outer yoke 24, and the gap 39 and goes back to the S pole of the permanent magnet 33, and static magnetic fields are generated in the gap 38 and the gap 39. In the inner
15 yoke 22 and the outer yoke 24, the magnetic flux circulates in the planes of the thin plates 23 and 25.

When AC current is supplied to the coil 32, different magnetic poles are alternately generated in axial direction on the magnetic poles 28, 29, and 30. By the magnetically attracting and repelling actions of the permanent magnets 33 and
20 34 and the movable unit 21, thrust force is generated in proportional to the magnitude of electric current flowing through the coil 32 and to the magnetic flux density of the permanent magnets 33 and 34. As a result, the piston 82 is reciprocally moved together with the movable unit 21. When the pressure in the compression chamber 84 is low, expanded gas is sucked into the compression
25 chamber 84 via the suction valve 85. When the pressure in the chamber is high,

compressed gas is sucked into the compression chamber 84 via the discharge valve 86, and it works as a linear compressor 80.

The direct-driven type linear motor 87 is integrated with the piston 82, and the piston 82 is reciprocally moved within the cylinder 81 as the movable unit 21 of the linear motor 87 is reciprocally moved. The mechanical sliding loss is generated in the linear compressor 80 only between the piston 82 and the cylinder 81. Therefore, mechanical sliding loss of the linear compressor can be reduced, and compressor efficiency can be increased.

The magnetic flux 31 generated from the permanent magnets 33 and 34 circulates in the planes of the thin plates 23 and 25 in the outer yoke 24. When the magnetic flux 31 circulates in the planes of the thin plates 23 and 25, it generates eddy current in the direction perpendicular to the magnetic flux 31. This is an electric current, which is proportional to square of the magnetic flux density and is also proportional to square of plate pressure of the yoke material. The inner yoke 22 and the outer yoke 24 have high magnetic permeability and have the insulated surfaces and these yokes are formed by laminating a multiple of thin plates 23 and 25. Therefore, it is possible to eliminate generation of eddy current almost completely, and iron loss is extensively reduced. Thus, compressor efficiency can be improved.

Because the inner yoke 22 and the outer yoke 24 are formed by laminating a multiple of thin plates 23 and 25 in simple manner, the linear compressor 80 can be produced in simple manner.

In the above, description has been given on an example where the coil 32 is wound on the outer yoke 24, while the coil 32 may be wound on the inner yoke 22.

In the above, description has been given on an example having 3 magnetic

poles, while it is also possible to design in such manner that the inner yoke 22 and the outer yoke 24, the magnets 33 and 34, and the coil 32 are connected in series in axial direction.

As described above, the linear motor of the present embodiment comprises a
5 movable unit of cylindrical shape having the central axis at the intersection of X-axis and Y-axis, an inner yoke arranged on inner side of the movable unit with a given spacing in radial direction of the movable unit and being formed by laminating a multiple of thin plates each in approximately rectangular shape and having high magnetic permeability in axial direction of one of X-axis or Y-axis, an outer yoke
10 arranged on outer side of the movable unit with a given spacing in radial direction of the movable unit and being formed by laminating a multiple of thin plates each in approximately rectangular shape and having high magnetic permeability in the same direction as the thin plates of the inner yoke, a base in planar shape for retaining the inner yoke and the outer yoke, a cylinder mounted so as to be positioned at the
15 center of X-axis and Y-axis, the movable unit being designed in such manner that a pair of C-shaped or cylindrical permanent magnets magnetized from the inner yoke side to the outer yoke side are retained in a gap between the inner yoke and the outer yoke, a piston arranged at forward end of a shaft integrated with the movable unit and placed in the cylinder, and a spring mounted on the shaft. Even when the
20 permanent magnets are disposed at deviated positions closer to the inner yoke or the outer yoke at the time of manufacture, the force to directly attract the permanent magnets toward the inner yoke or the outer yoke is not increased. Therefore, sliding loss between the piston and the cylinder is not increased, and the linear motor can be manufactured in easier manner.

25

INDUSTRIAL APPLICABILITY

As described above, according to an aspect of the present invention, the linear motor of the invention comprises a movable unit in cylindrical shape having the central axis at the intersection of X-axis and Y-axis, an inner yoke arranged on inner side of the movable unit with a given spacing in radial direction of the movable unit and being formed by laminating a multiple of thin plates each in approximately rectangular shape and having high magnetic permeability arranged in axial direction of one of X-axis or Y-axis, an outer yoke arranged on outer side of the movable unit with a given spacing in radial direction of the movable unit and being formed by laminating a multiple of thin plates each in approximately rectangular shape and having high magnetic permeability arranged in the same direction as the thin plates of the inner yoke, and forming a first magnetic pole, a second magnetic pole and a third magnetic pole by arranging two slots being cut out in the laminating direction of the thin plates, a coil wound on the second magnetic pole of the outer yoke and for generating alternately different magnetic poles at the first magnetic pole, the second magnetic pole and the third magnetic pole, a base for retaining the inner yoke and the outer yoke, bearings mounted on the base to be positioned at the center of X-axis and Y-axis and a pair of permanent magnets magnetized in a direction connecting the inner yoke with the outer yoke and mounted on the movable unit, the magnets are retained in a gap between the inner yoke and the outer yoke with a given spacing in parallel to the central axis so that directions of magnetization are opposite to each other. Because the movable unit is designed in cylindrical shape, even when the shaft is arranged at axially rotated position during manufacture, the thrust force of the linear motor is not decreased. Iron loss of the inner yoke and the outer yoke is reduced, and motor efficiency is improved. Also, this facilitates the

manufacture of the linear motor.

According to another aspect of the present invention, in addition to the invention described in claim 1, it is designed in such manner that a pair of permanent magnets magnetized in radial direction around the central axis are disposed in a gap
5 between the inner yoke and the outer yoke with a given spacing in parallel to the central axis so that directions of magnetization are opposite to each other. Even when the permanent magnets are disposed at deviated positions to closer to the inner yoke or the outer yoke during manufacture, the force to directly attract the permanent magnets toward the inner yoke or the outer yoke is not increased, and
10 sliding loss on the sliding portions can be decreased.

According to still another aspect of the invention, the inner yoke in the invention described in claim 1 or 2 is formed by thin plates of the same shape and the same dimension, and the outer yoke is formed by thin plates of the same shape and the same dimension. Thus, the inner yoke and the outer yoke can be produced in
15 easier manner, and this facilitates the manufacture of the linear motor.

According to yet still another aspect of the present invention, in the invention described in claim 1 or 2, radius of curvature of inner periphery of the outer yoke is equal to radius of curvature of inner periphery of the slot, and radius of curvature of outer periphery of the outer yoke is equal to radius of curvature of outer periphery of
20 the slot. The radius of curvature of outer periphery of the outer yoke or the slot is greater than the radius of curvature of outer periphery of the outer yoke or the slot. This makes it possible to design the linear motor in compact size.

According to yet still another aspect of the present invention, in addition to the invention described in claim 1, it is designed in such manner that outer periphery of
25 each of the two outermost sides in laminating direction of the thin plates of the inner

yoke and an end surface of the permanent magnet are on a line, which connects inner periphery of each of the outermost sides in laminating direction of the thin plates of the outer yoke with the intersection of X-axis and Y-axis. As a result, it is possible to reduce the amount of magnets.

5 According to yet still another aspect of the present invention, in the invention described in claim 1 or 2, two inner yokes are arranged symmetrically with respect to Y-axis, and the two inner yokes are integrated by two inner yoke support members disposed inside the two inner yokes and positioned separately in direction of Y-axis. Thus, the inner yokes are integrated to a single component, and this facilitates the
10 assembling procedure.

According to yet still another aspect of the present invention, in the invention described in claim 1 or 2, two outer yokes are arranged symmetrically with respect to Y-axis, and the two outer yokes are integrated by two outer yoke support members disposed on each of the outermost sides in laminating direction of the thin plates of
15 the two outer yokes. Thus, the two outer yokes are integrated to a single component, and this facilitates the assembling procedure.

According to still another aspect of the present invention, the invention provides a linear motor, which comprises a movable unit in cylindrical shape having its central axis at the intersection of X-axis and Y-axis, an inner yoke arranged on inner side of
20 the movable unit with a given spacing in radial direction of the movable unit and being formed by laminating a multiple of thin plates each in approximately rectangular shape and having high magnetic permeability in the axial direction of one of X-axis or Y-axis, an outer yoke arranged on outer side of the movable unit with a given spacing in radial direction of the movable unit and being formed by laminating
25 a multiple of thin plates each in approximately rectangular shape and having high

magnetic permeability in the same direction as the thin plates of the inner yoke, a base in planar shape for retaining the inner yoke and the outer yoke, a cylinder mounted on the base to be positioned at the center of X-axis and Y-axis, a pair of permanent magnets magnetized in a direction connecting the inner yoke with the

5 outer yoke and disposed on the movable unit to be retained in a gap between the inner yoke and the outer yoke with a given spacing in parallel to the central axis so that directions of magnetization are opposite to each other, a piston mounted at forward end of a shaft integrated with the movable unit and placed in the cylinder, and a spring mounted on the shaft. Even when the permanent magnets are at

10 deviated position closer to the inner yoke or the outer yoke during manufacture, the force to directly attract the permanent magnets toward the inner yoke or the outer yoke is not increased. Therefore, sliding loss between the piston and the cylinder is not increased, and this facilitates the manufacture of the linear motor.

WHAT IS CLAIMED IS:

1. A linear motor, comprising a movable unit in cylindrical shape having central axis at the intersection of X-axis and Y-axis, an inner yoke arranged on inner side of the movable unit with a given spacing in radial direction of the movable unit and being formed by laminating a multiple of thin plates each in approximately rectangular shape and having high magnetic permeability in parallel to one of X-axis or Y-axis, an outer yoke arranged on outer side of the movable unit with a given spacing in radial direction of the movable unit, being formed by laminating a multiple of thin plates each in approximately rectangular shape and having high magnetic permeability arranged in the same direction as the thin plates of the inner yoke, and forming a first magnetic pole, a second magnetic pole, and a third magnetic pole by arranging two slots cut out in the laminating direction of the thin plates, a coil wound on the second magnetic pole of the outer yoke and for forming alternately different magnetic poles at the first magnetic pole, the second magnetic pole, and the third magnetic pole, a base for retaining the inner yoke and the outer yoke, bearings mounted on the base to be positioned at the center of X-axis and Y-axis, a pair of permanent magnets magnetized in a direction to connect the inner yoke with the outer yoke and arranged on the movable unit to be retained in a gap between the inner yoke and the outer yoke with a given spacing in parallel to the central axis so that directions of magnetization are opposite to each other, and a shaft integrated with the movable unit and pivotally supported on the bearings.

2. A linear motor according to claim 1, wherein a pair of permanent magnets magnetized in radial direction around the central axis are arranged with a given spacing in parallel to the central axis so that directions of magnetization are opposite

to each other, and said magnets being retained in a gap between the inner yoke and the outer yoke.

3. A linear motor according to claim 1 or 2, wherein the inner yoke is formed
5 by laminating a multiple of thin plates of the same shape and the same dimension,
and the outer yoke is formed by laminating a multiple of thin plates of the same
shape and the same dimension.

4. A linear motor according to claim 1 or 2, wherein radius of curvature of
10 inner periphery of the outer yoke is equal to radius of curvature of inner periphery of
the slot, and radius of curvature of outer periphery of the outer yoke is equal to radius
of curvature of outer periphery of the slot, and radius of curvature of outer periphery
of the outer yoke or the slot is greater than the radius of curvature of the inner
periphery of the outer yoke or the slot.

15

5. A linear motor according to claim 2, wherein outer peripheral end of each
of the outermost sides in laminating direction of the thin plates of the inner yoke and
an end surface of the permanent magnet are on a line, which connects inner
peripheral end of each of the outermost sides in laminating direction of the thin plates
20 of the outer yoke with the intersection of X-axis and Y-axis.

6. A linear motor according to claim 1 or 2, wherein two inner yokes are
arranged symmetrically with respect to Y-axis, and the two inner yokes are
integrated by two inner yoke support members disposed inside the inner yoke and
25 positioned separately in direction of Y-axis.

7. A linear motor according to claim 6, wherein the inner yoke support members are made of a nonmagnetic material.

8. A linear motor according to claim 1 or 2, wherein two outer yokes are
5 arranged symmetrically with respect to Y-axis, and the two outer yokes are integrated by two outer yoke support members disposed on each of the outermost sides in laminating direction of the thin plates of the outer yokes.

9. A linear motor according to claim 8, wherein said outer yoke support
10 members are made of a nonmagnetic material.

10. A linear compressor, comprising a movable unit in cylindrical shape and having the central axis at the intersection of X-axis and Y-axis, an inner yoke arranged on inner side of the movable unit with a given spacing in radial direction of
15 the movable unit and being formed by laminating a multiple of thin plates each in approximately rectangular shape and having high magnetic permeability arranged in parallel to one of X-axis or Y-axis, an outer yoke arranged on outer side of the movable unit with a given spacing in radial direction of the movable unit, being formed by laminating a multiple of thin plates each in approximately rectangular
20 shape and having high magnetic permeability arranged in the same direction as the thin plates of the inner yoke, and forming a first magnetic pole, a second magnetic pole and a third magnetic pole by arranging two slots cut out in the laminating direction of the thin plates, a coil wound on the second magnetic pole of the outer yoke and forming alternately different magnetic poles at the first magnetic pole, the
25 second magnetic pole and the third magnetic pole, a base in planar shape for

ABSTRACT

The present invention provides a linear motor, which can improve motor efficiency and which can be manufactured by simplified procedure. The linear motor of the present invention comprises a movable unit 21 in cylindrical shape and having the central axis at the intersection of X-axis and Y-axis, an inner yoke 22 arranged on inner side of the movable unit 21 with a given spacing in radial direction of the movable unit 21 and being formed by laminating a multiple of thin plates each in approximately rectangular shape and having high magnetic permeability arranged in direction of X-axis, an outer yoke 24 arranged on outer side of the movable unit with a given spacing in radial direction of the movable unit 21 and being formed by laminating a multiple of thin plates 25 each in approximately rectangular shape arranged in the same direction as the thin plates 23 of the inner yoke 22, and a pair of permanent magnets 33 and 34 magnetized in a direction from the inner yoke 22 to the outer yoke 24.

Therefore, the thrust force of the linear motor is not turned to unstable, and motor efficiency can be improved, and this facilitates the manufacture of the linear motor.

FIG. 1

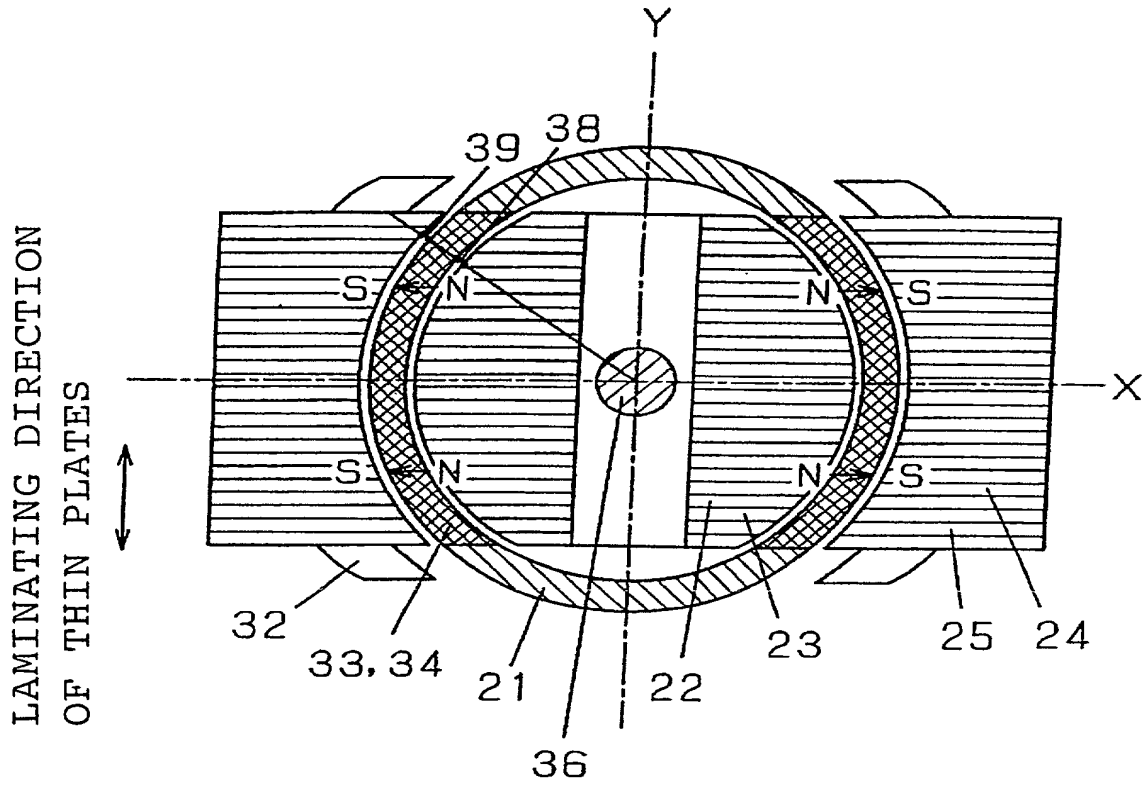


FIG. 2

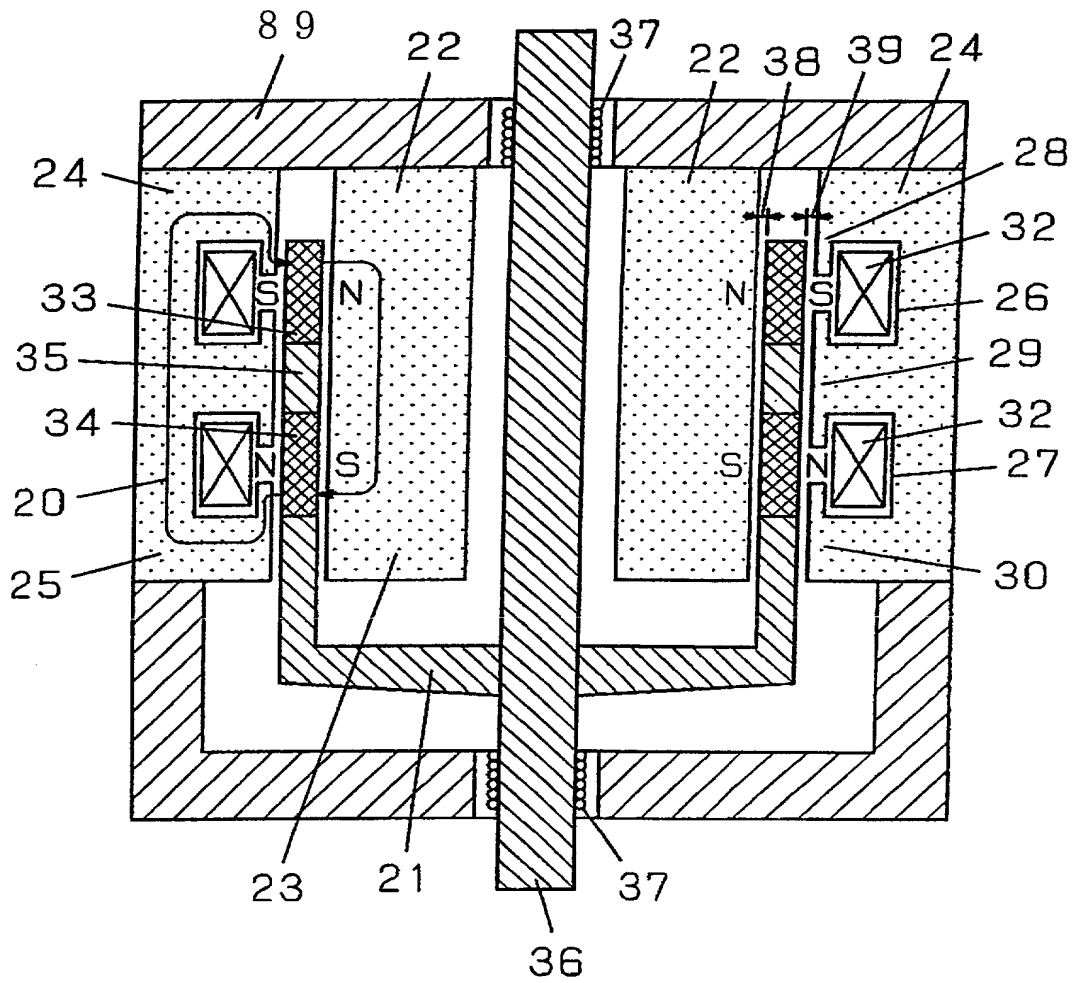


FIG. 3

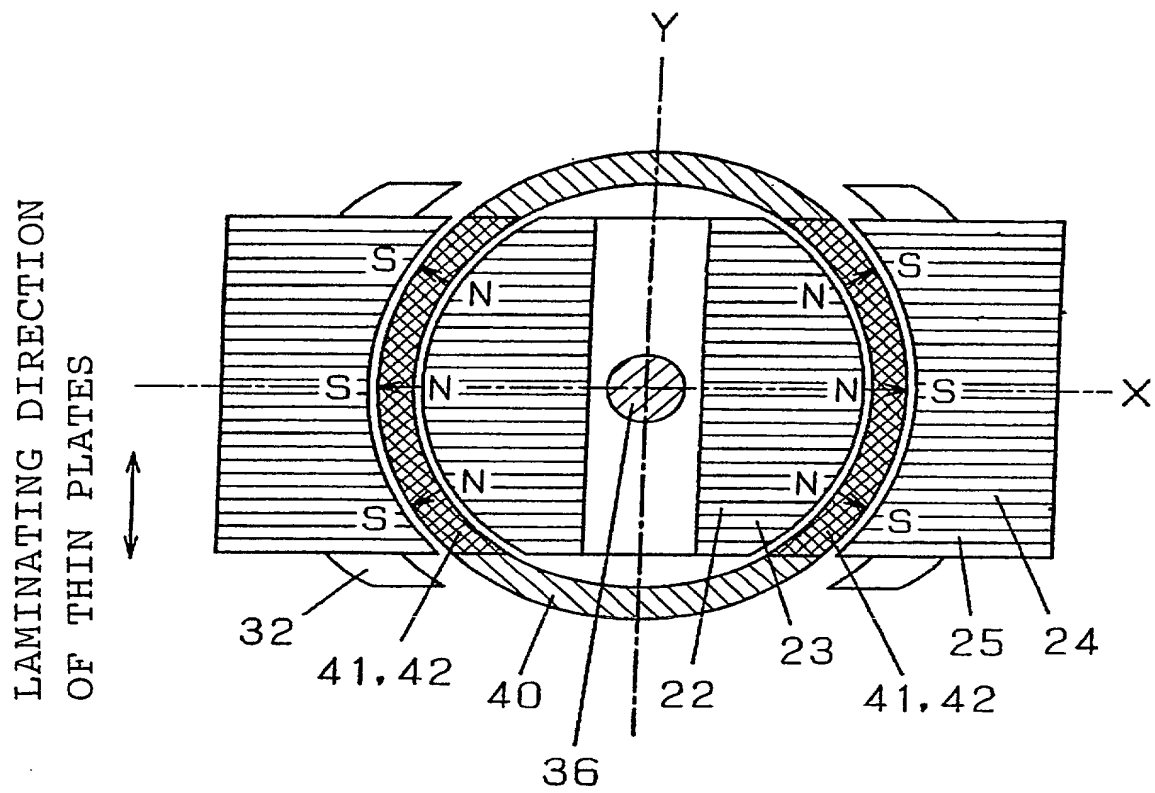


FIG. 4

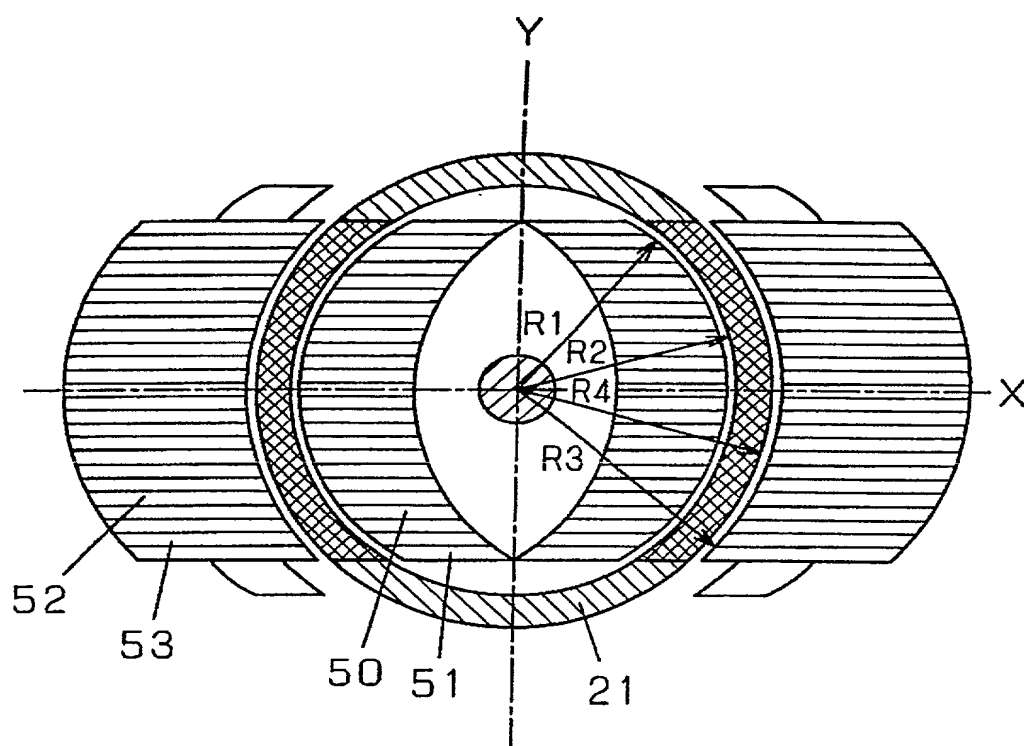


FIG. 5

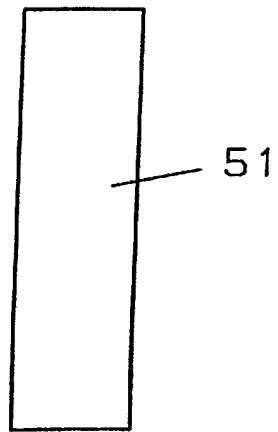
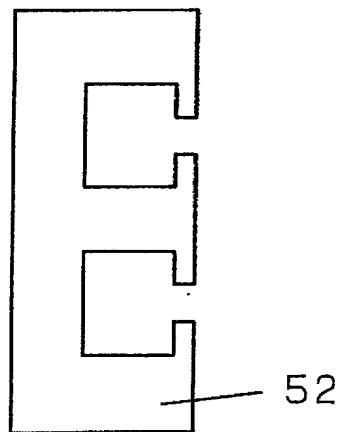


FIG. 6



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FIG. 7

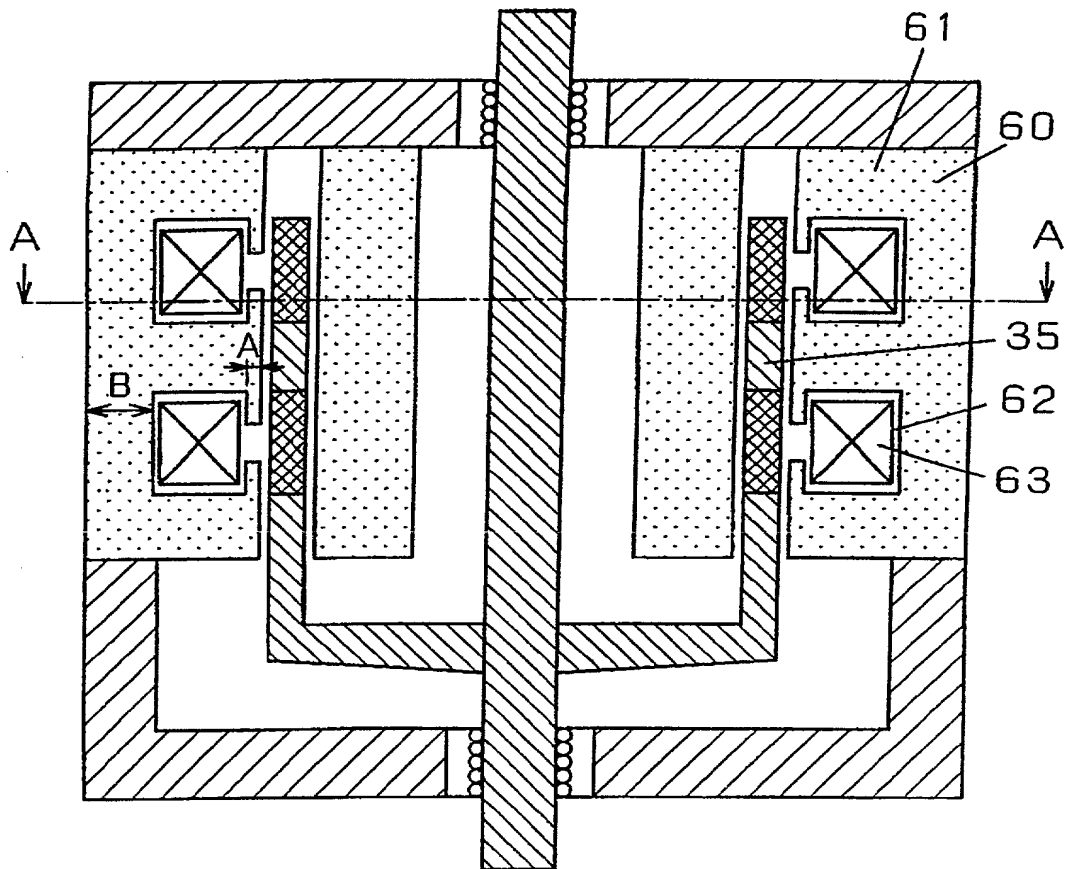


FIG. 8

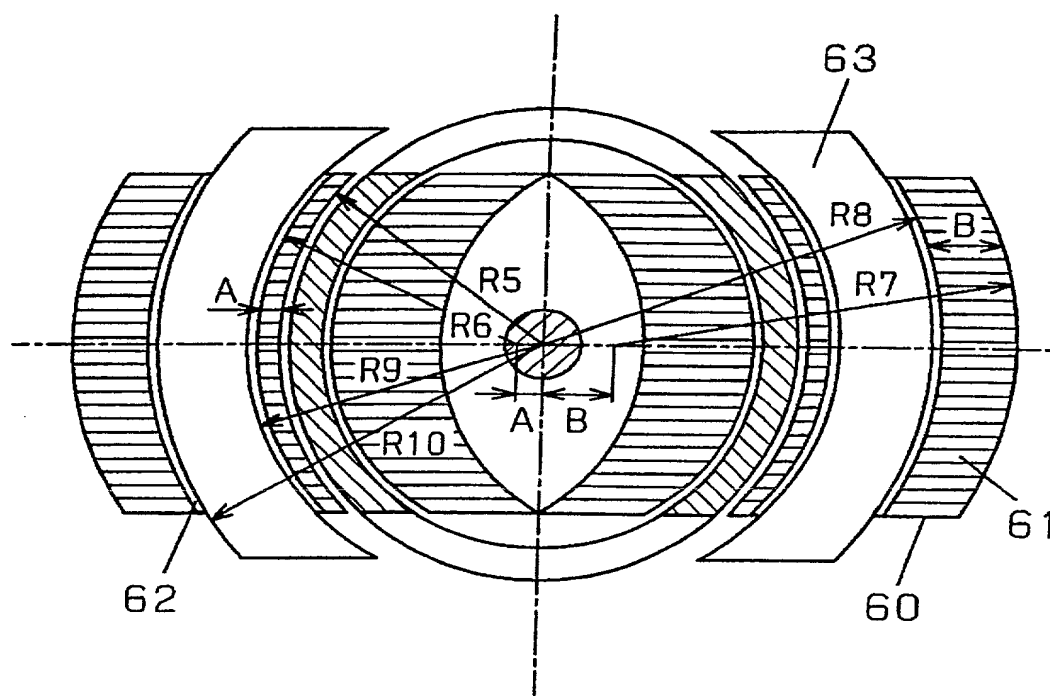


FIG. 9

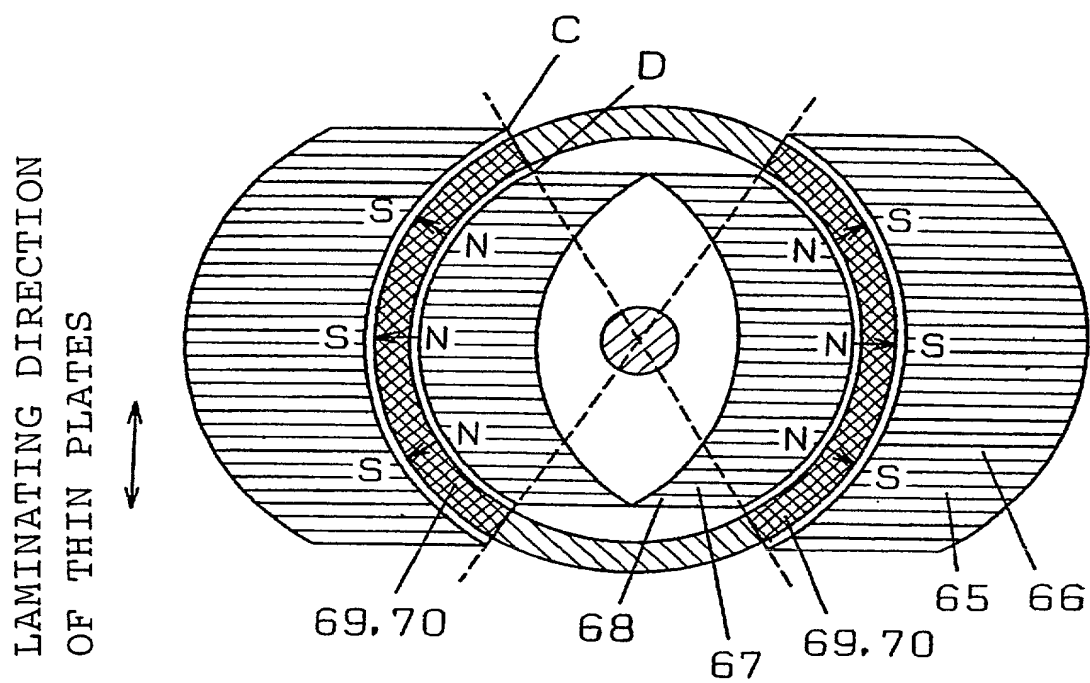


FIG. 10

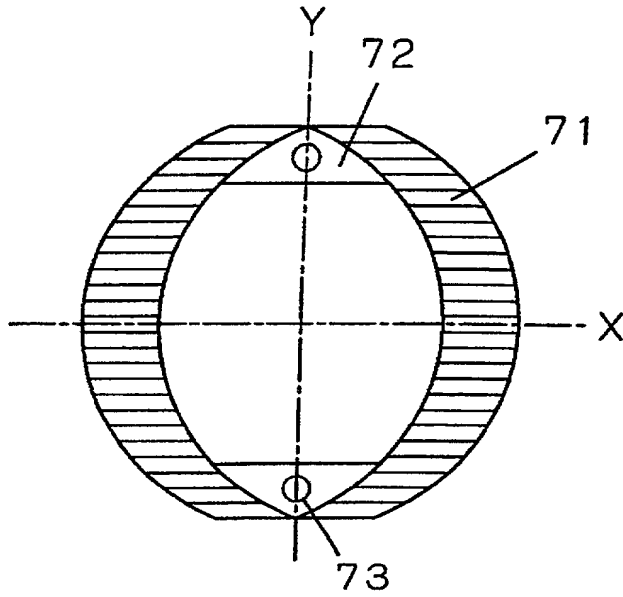


FIG. 11

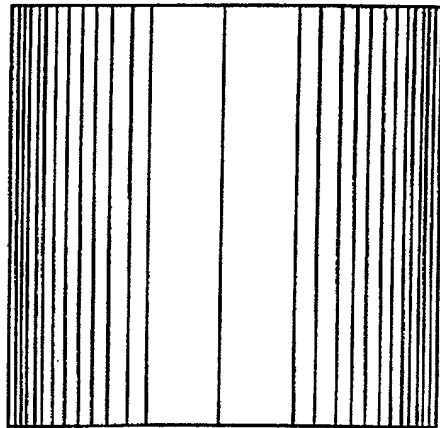


FIG. 12

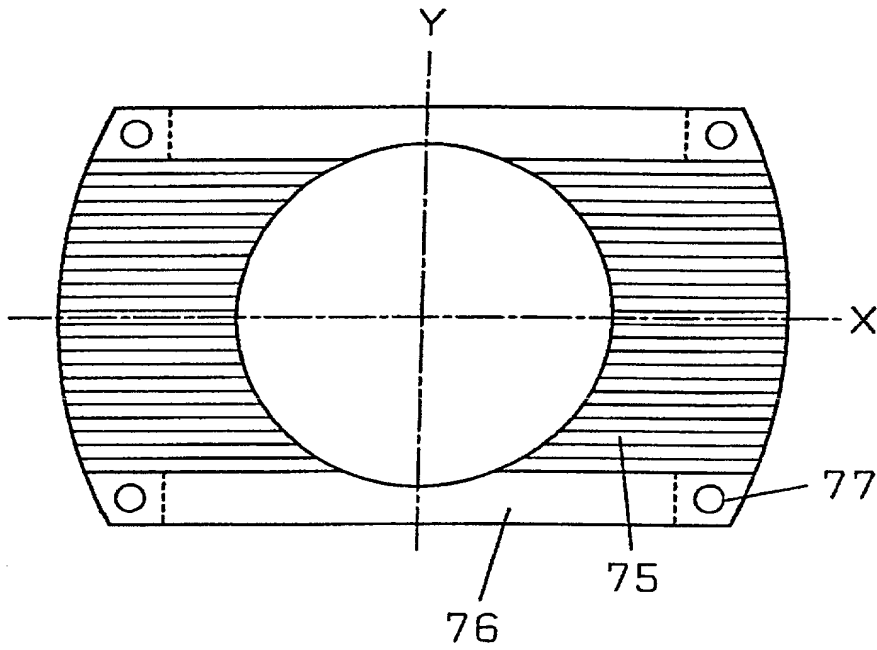


FIG. 13

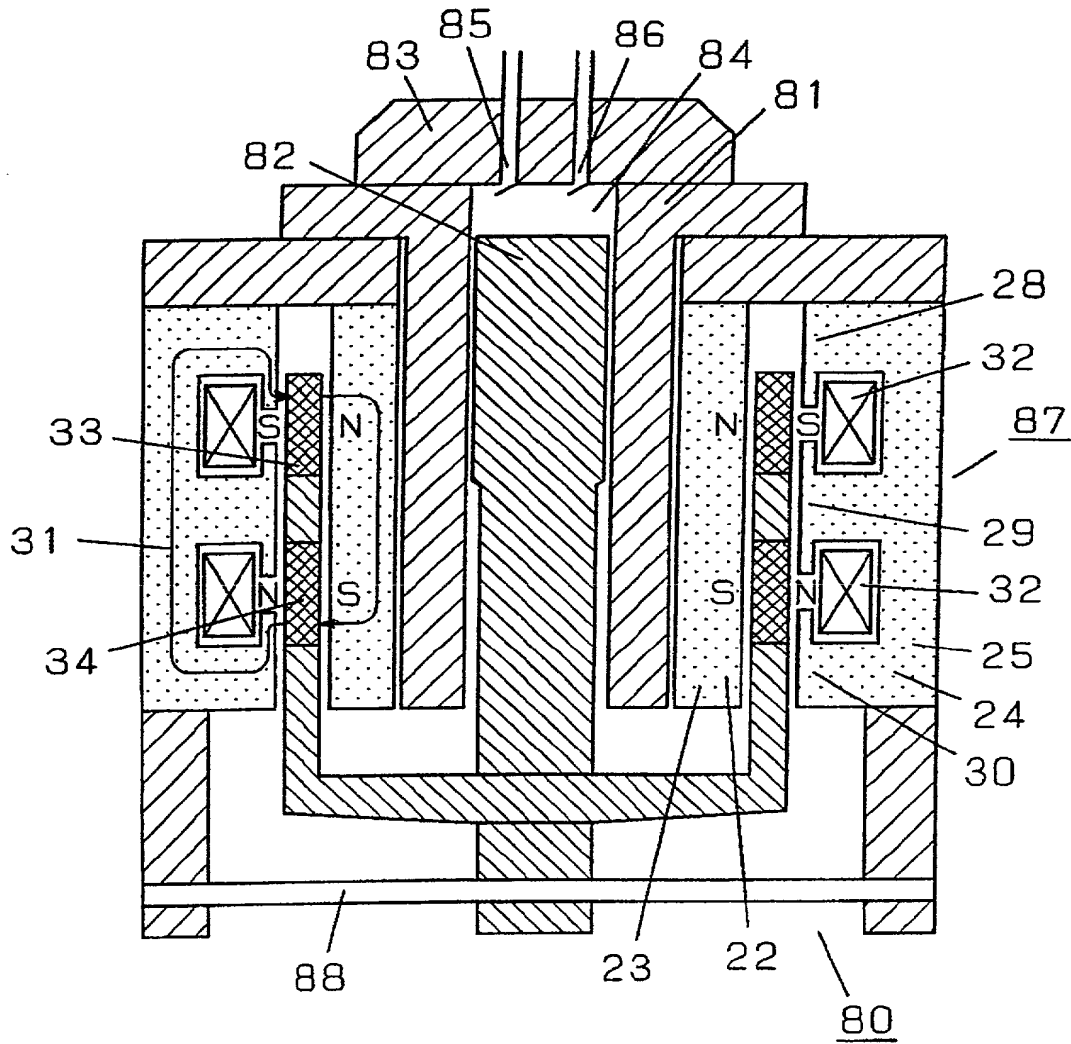


FIG. 14

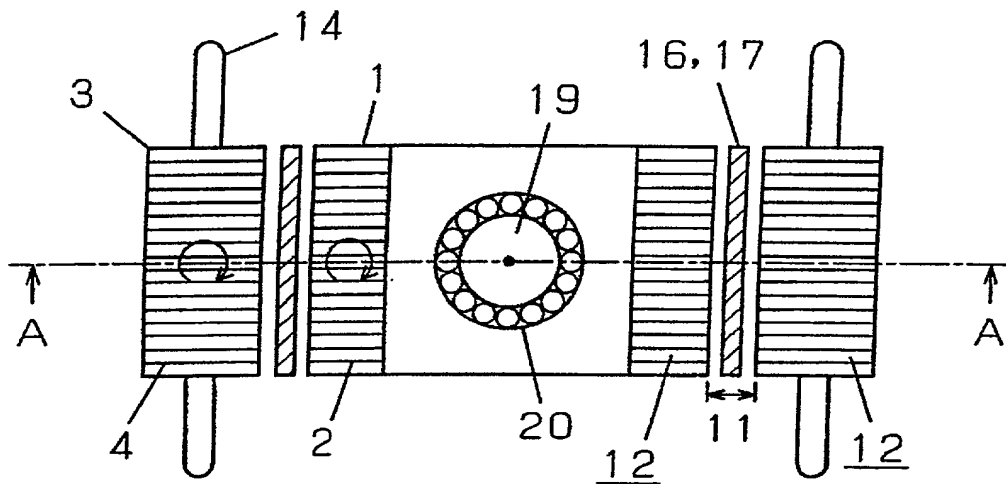
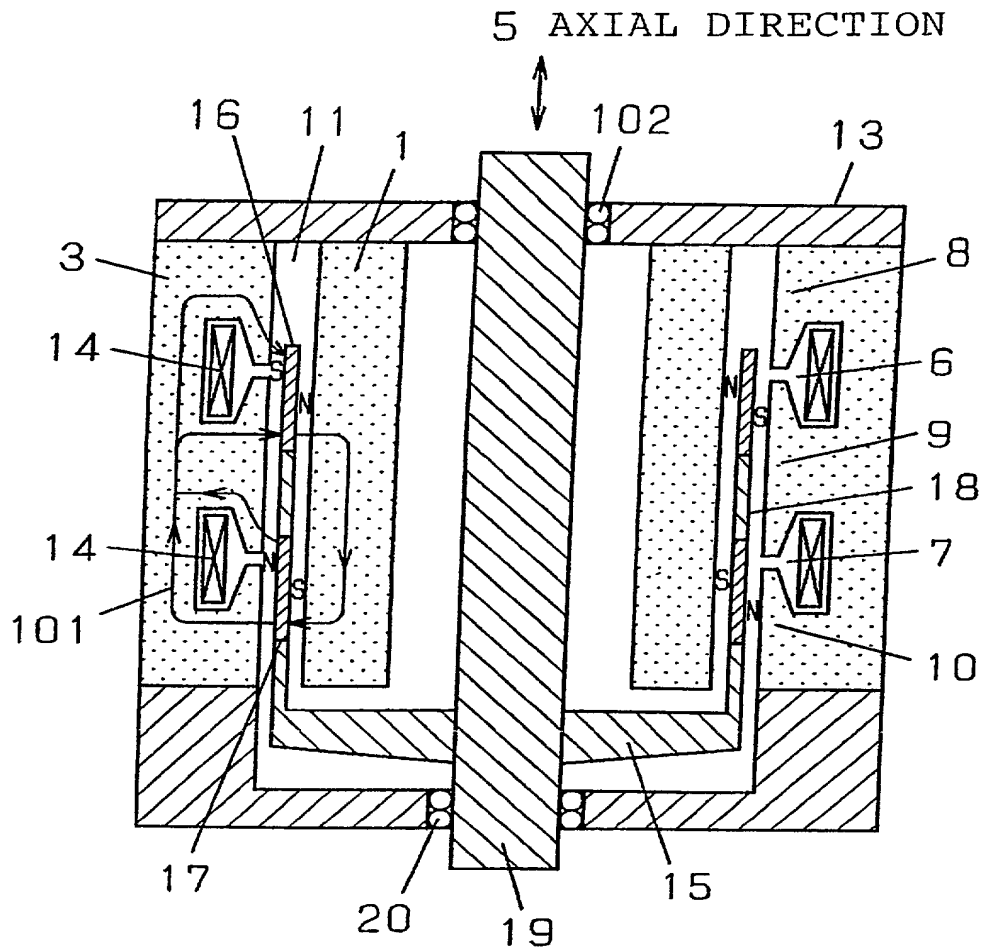


FIG. 15



DECLARATION FOR PATENT APPLICATION

As a below-named inventor, I hereby declare that:

My residence, post office address and citizenship are as stated below next to my name.

I believe I am the original, first and sole inventor (if only one name is listed below) or an original, first and joint inventor (if plural names are listed below) of the subject matter which is claimed and for which a patent is sought on the invention entitled: LINEAR MOTOR

the specification of which: (check one)

☐ is attached hereto. ☒ was filed on 24 October, 2000, as United States Patent Application Serial No. or PCT International Application Number PCT/JP00/07410 and was amended on _____ (if applicable).

I hereby state that I have reviewed and understand the contents of the above-identified specification, including the claims, as amended by any amendment referred to above.

I acknowledge the duty to disclose information which is material to the patentability of this application in accordance with 37 CFR § 1.56(a).

Prior Foreign Application(s): I hereby claim foreign priority benefits under 35 U.S.C. § 119(a)-(d) or § 365(b) of any foreign application(s) for patent or inventor's certificate listed below, or § 365(a) of any PCT international application which designated at least one country other than the United States of America, listed below and have also identified below any foreign application for patent or inventor's certificate having a filing date before that of the application on which priority is claimed:

			Priority Claimed
<u>11-305063</u>	<u>JAPAN</u>	<u>27, October 1999</u>	<input checked="" type="checkbox"/> <input type="checkbox"/>
(Application No.)	(Country)	(Day/Month/Year Filed)	Yes No
			<input type="checkbox"/> <input type="checkbox"/>
(Application No.)	(Country)	(Day/Month/Year Filed)	Yes No
			<input type="checkbox"/> <input type="checkbox"/>
(Application No.)	(Country)	(Day/Month/Year Filed)	Yes No

I hereby claim the benefit under Title 35, United States Code § 119(e) of any United States provisional application(s) listed below:

Application No.	Filing Date
_____	_____

I hereby claim the benefit under 35 U.S.C. § 120 of any United States application(s) listed below and, insofar as the subject matter of each of the claims of this application is not disclosed in the prior United States application in the manner provided by 35 U.S.C. § 112, first paragraph, I acknowledge the duty to disclose material information as defined in 37 CFR § 1.56(a) which occurred between the filing date of the prior application and the national or PCT international filing date of this application:

(U.S. Application Serial No.)	(U.S. Filing Date)	(Status—patented, pending, abandoned)
_____	_____	_____
(U.S. Application Serial No.)	(U.S. Filing Date)	(Status—patented, pending, abandoned)
_____	_____	_____

I hereby appoint Elliott I. Pollock, Registration No. 16,906; George Vande Sande, Registration No. 17,276; Burton A. Amernick, Registration No. 24,852; Stanley B. Green, Registration No. 24,351; Richard Wiener, Registration No. 18,741; Townsend M. Belser, Jr., Registration No. 22,956; Morris Liss, Registration No. 24,510; Martin Abramson, Registration No. 25,787; George R. Pettit, Registration No. 27,369; Elzbieta Chlopecka, Registration No. 32,767; Eric J. Franklin, Registration No. 37,134; and Jeffri A. Kaminski, Reg. No. 42,709, my attorneys with full power of substitution and revocation, to prosecute this application and to transact all business in the Patent and Trademark Office connected therewith.

Send Correspondence and Direct Telephone Calls to:

Morris Liss
(202) 331-7111

Morris Liss
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P.O. Box 19088
Washington, D.C. 20036B3425 U.S.A.

I hereby declare that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements are made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under 18 U.S.C. § 1001 and that such willful false statements may jeopardize the validity of the application or any patent issued thereon.

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DECLARATION FOR PATENT APPLICATION

Page Two

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Full name of third joint inventor (if any): _____

Inventor's Signature _____

Date _____

Residence Address _____

Citizenship _____

Post Office Address _____

Full name of fourth joint inventor (if any): _____

Inventor's Signature _____

Date _____

Residence Address _____

Citizenship _____

Post Office Address _____

Full name of fifth joint inventor (if any): _____

Inventor's Signature _____

Date _____

Residence Address _____

Citizenship _____

Post Office Address _____

Full name of sixth joint inventor (if any): _____

Inventor's Signature _____

Date _____

Residence Address _____

Citizenship _____

Post Office Address _____

Full name of seventh joint inventor (if any): _____

Inventor's Signature _____

Date _____

Residence Address _____

Citizenship _____

Post Office Address _____

Full name of eighth joint inventor (if any): _____

Inventor's Signature _____

Date _____

Residence Address _____

Citizenship _____

Post Office Address _____